

FINITE STATE MACHINES

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Finite State Machines (FSMs)

- Finite-state machine (FSM) is a mathematical model used to design computer programs and digital logic circuits.
- Any Circuit with Memory Is a Finite State Machine
 - ▣ Even computers can be viewed as huge FSMs
- Design of FSMs Involves
 - ▣ Defining states
 - ▣ Defining transitions between states
 - ▣ Optimization / minimization
- Above Approach Is Practical for Small FSMs Only

State diagram & State assignment

- A **state diagram** is a type of diagram to describe the behavior of systems.
- State diagrams require that the system described is composed of a finite number of states
- **State assignment** is a specification have been given to a combination of flip-flops and combinational logic
- State assignment is to the number of present states in a particular circuit
- N-number of flip flop 2^N state assignment

Types Of FSM's

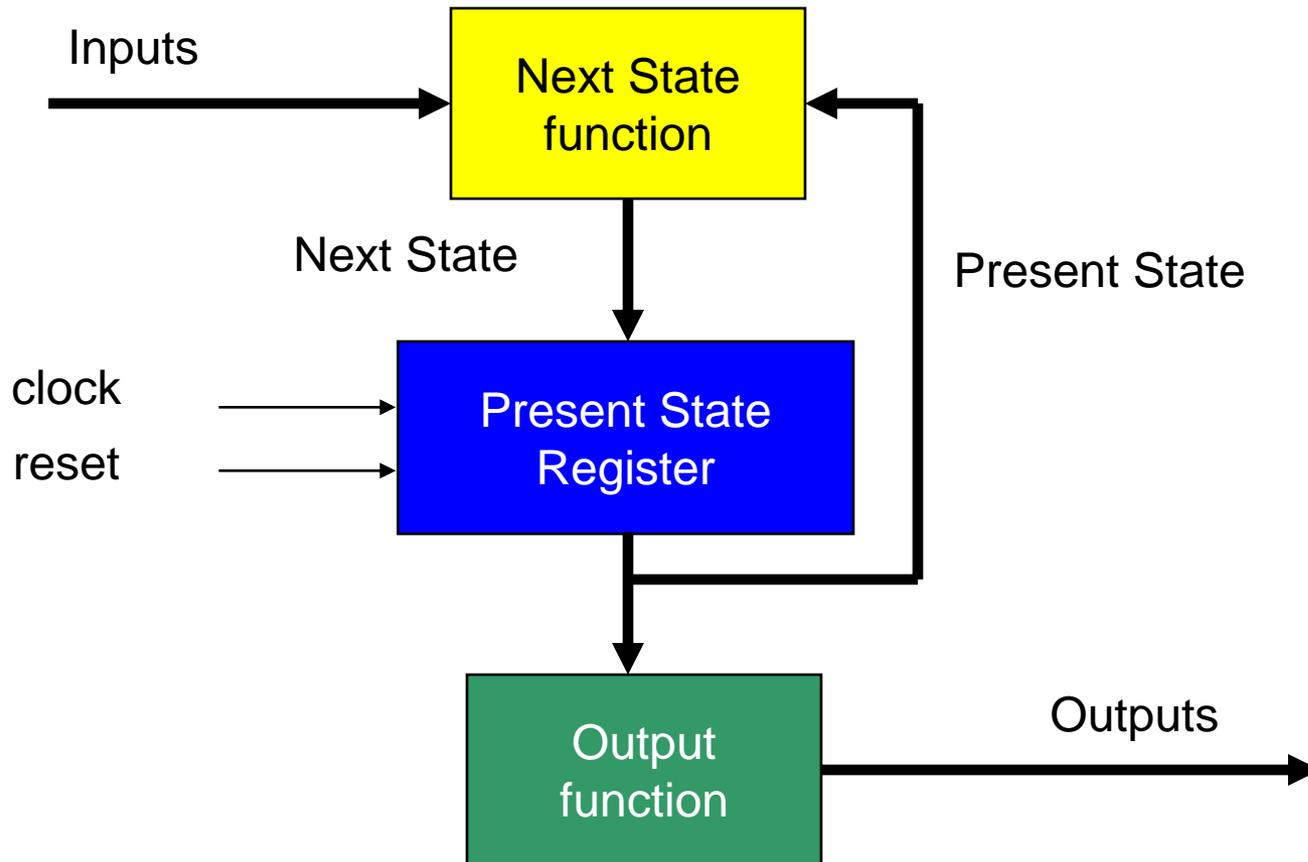


There are two basic ways to design clocked sequential circuits.

1. Mealy Machine
2. Moore Machine

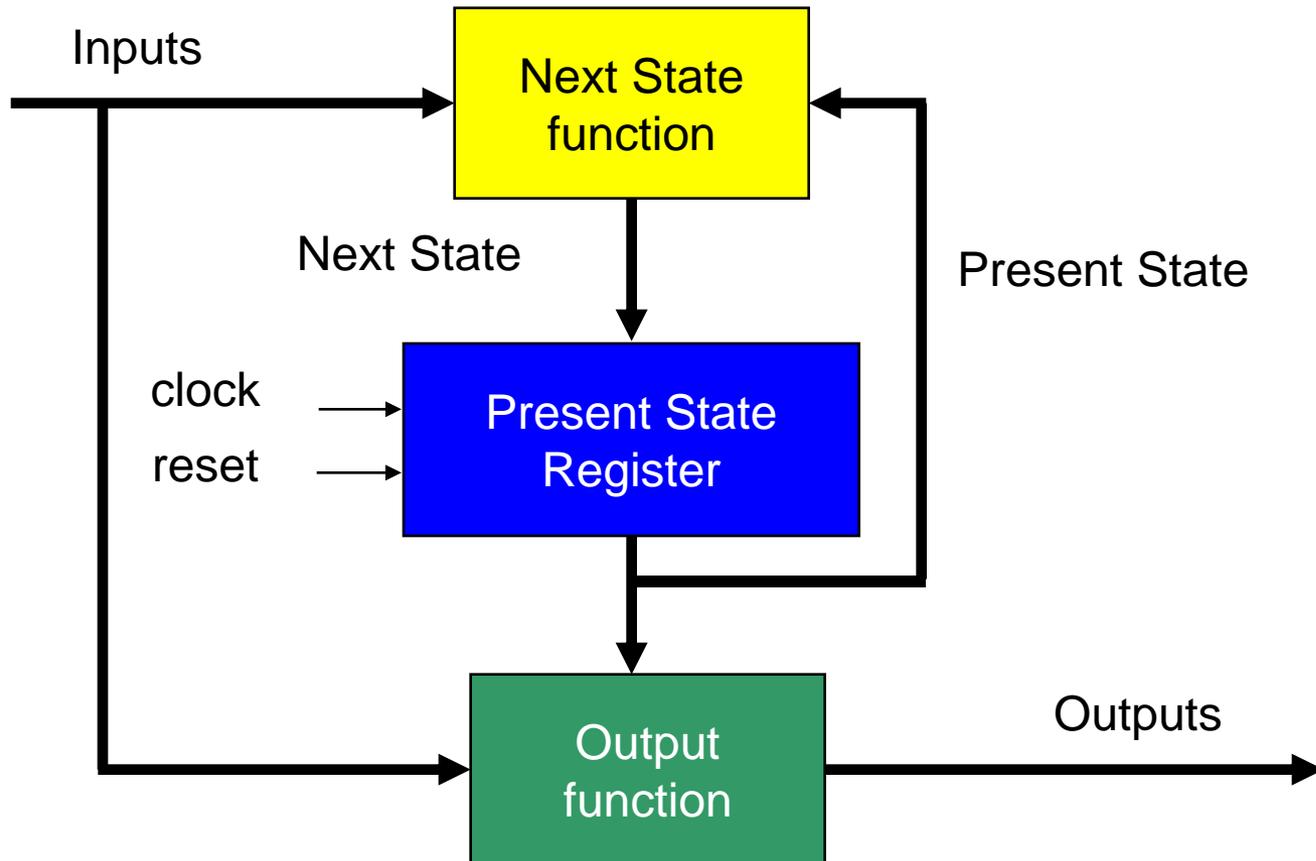
Moore FSM

- Output Is a Function of a Present State Only

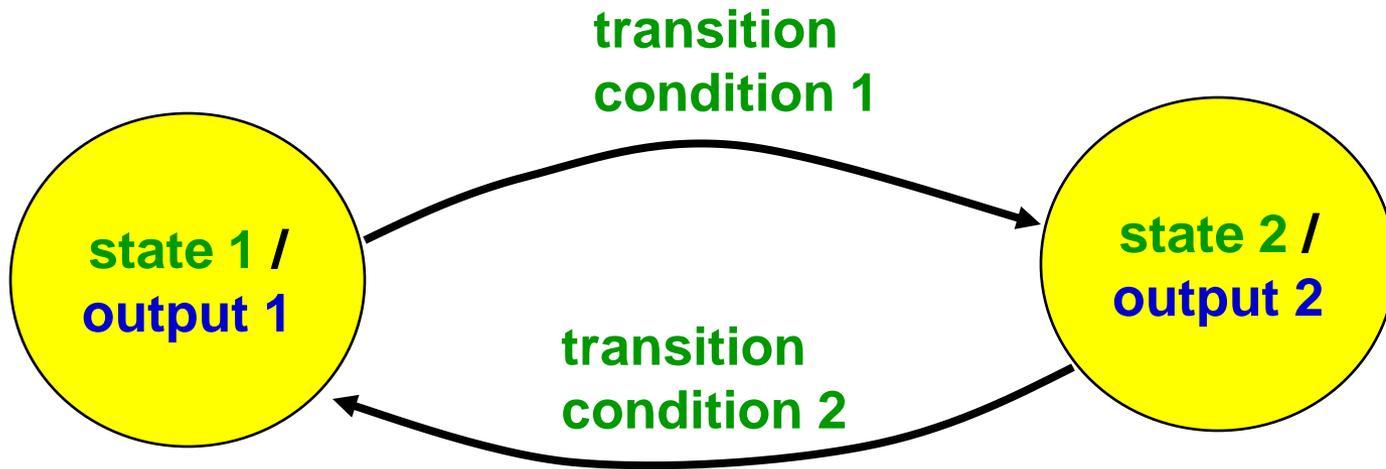


Mealy FSM

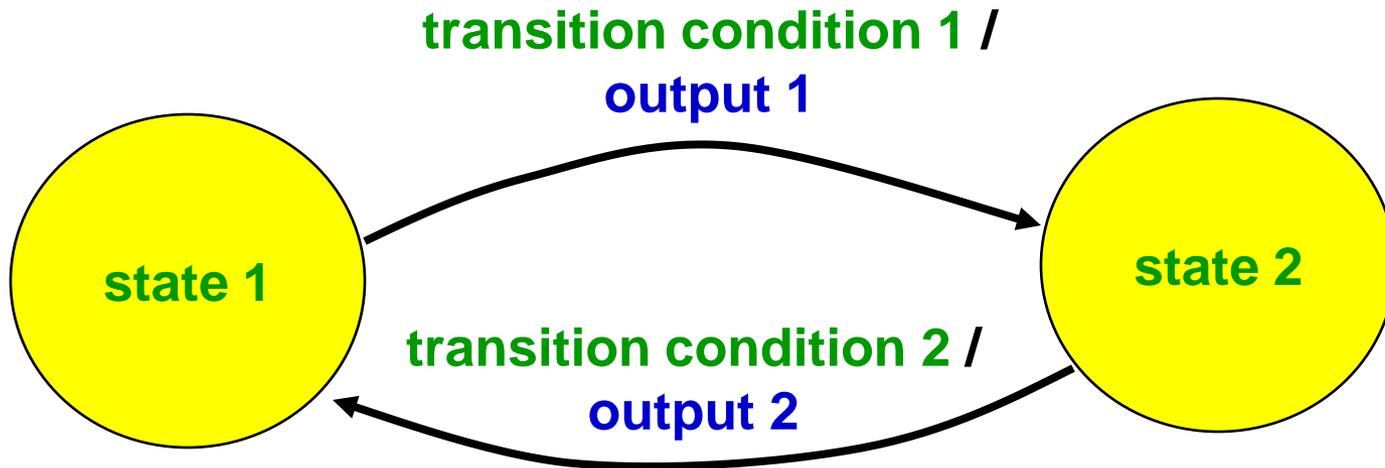
- Output Is a Function of a Present State and Inputs



Moore Machine



Mealy Machine



Moore vs. Mealy FSM (1)

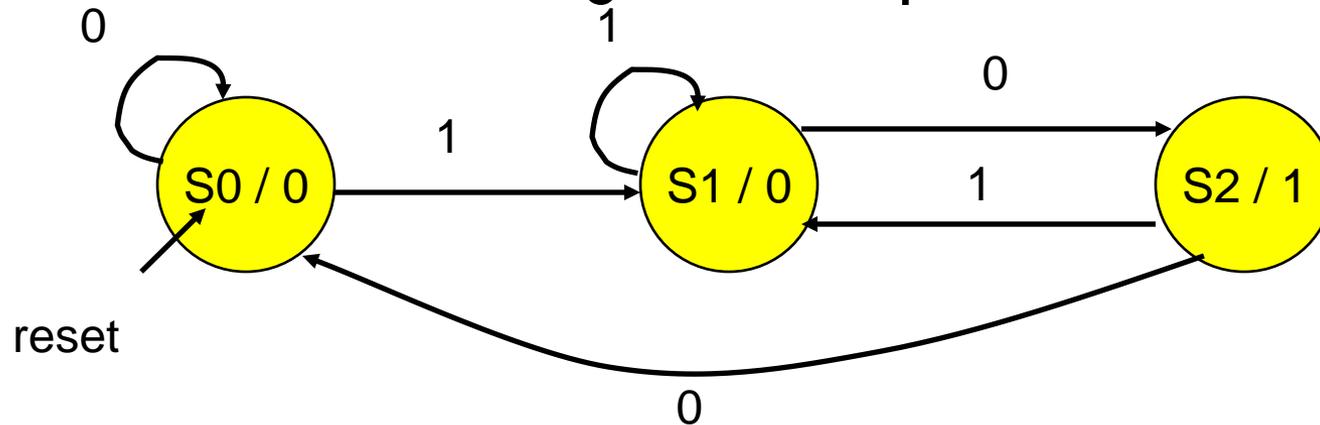
- Moore and Mealy FSMs Can Be Functionally Equivalent
- Mealy FSM Has Richer Description and Usually Requires Smaller Number of States
 - Smaller circuit area

Moore vs. Mealy FSM (2)

- Mealy FSM Computes Outputs as soon as Inputs Change
 - ▣ Mealy FSM responds one clock cycle sooner than equivalent Moore FSM

Moore FSM - Example 1

- Moore FSM that Recognizes Sequence "10"



Meaning
of states:

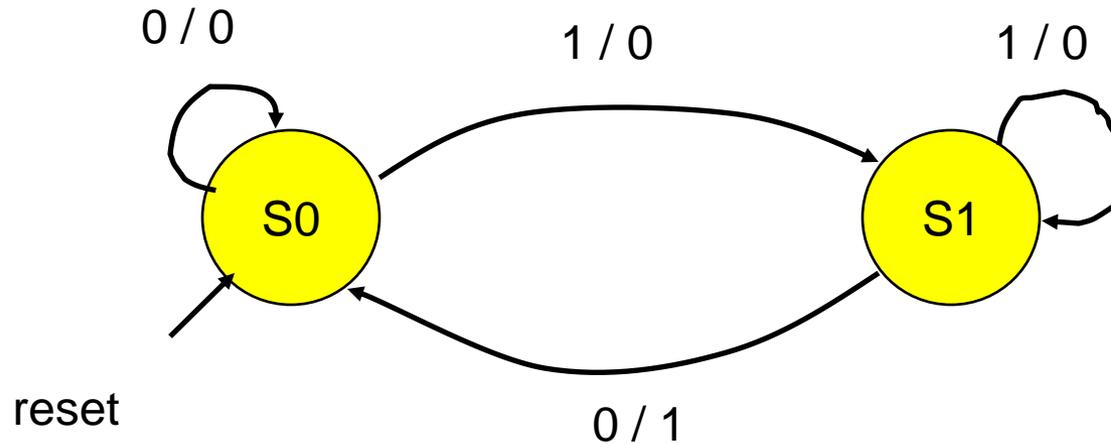
S0: No
elements
of the
sequence
observed

S1: "1"
observed

S2: "10"
observed

Mealy FSM - Example 1

- Mealy FSM that Recognizes Sequence “10”

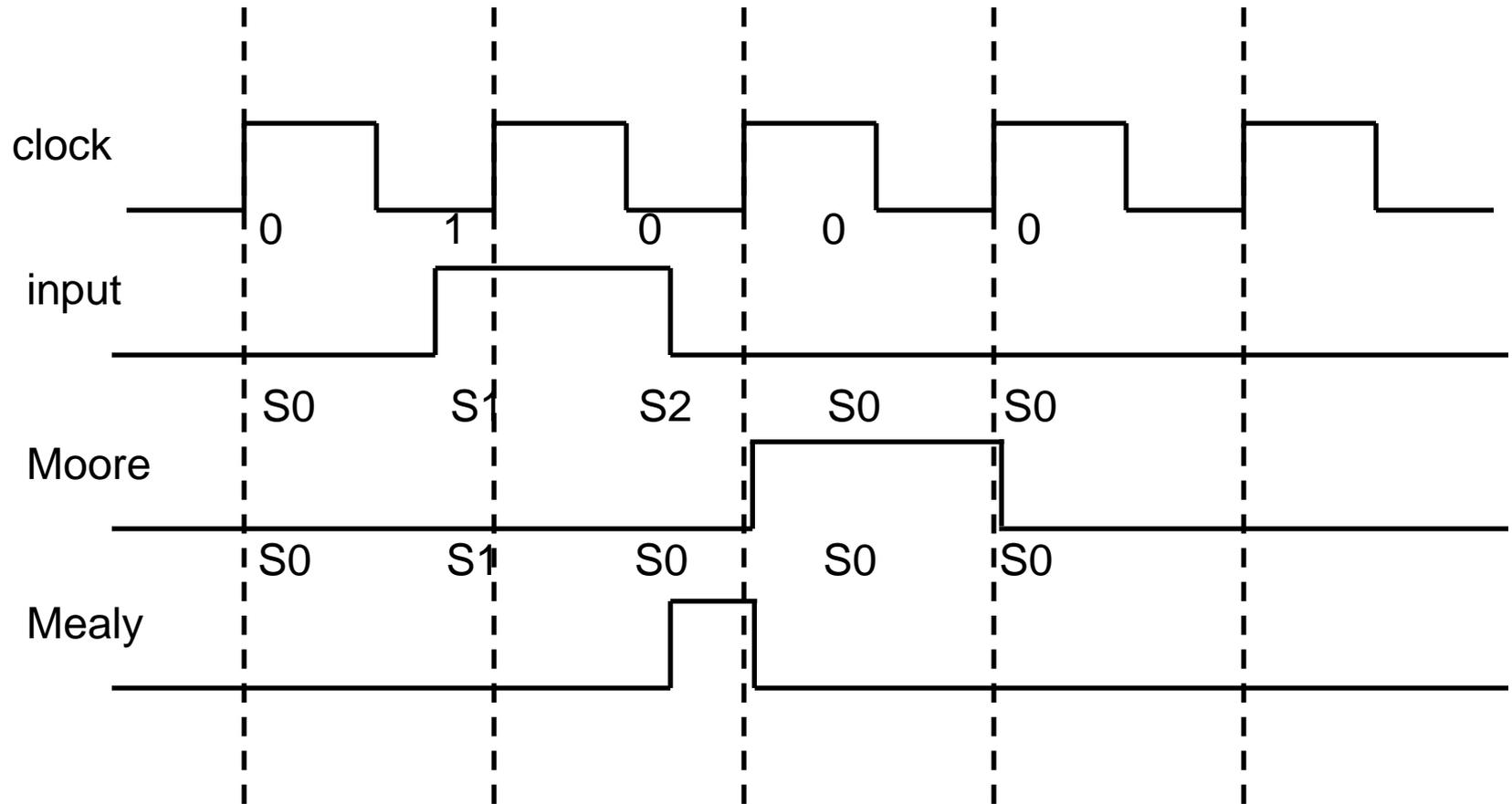


Meaning
of states:

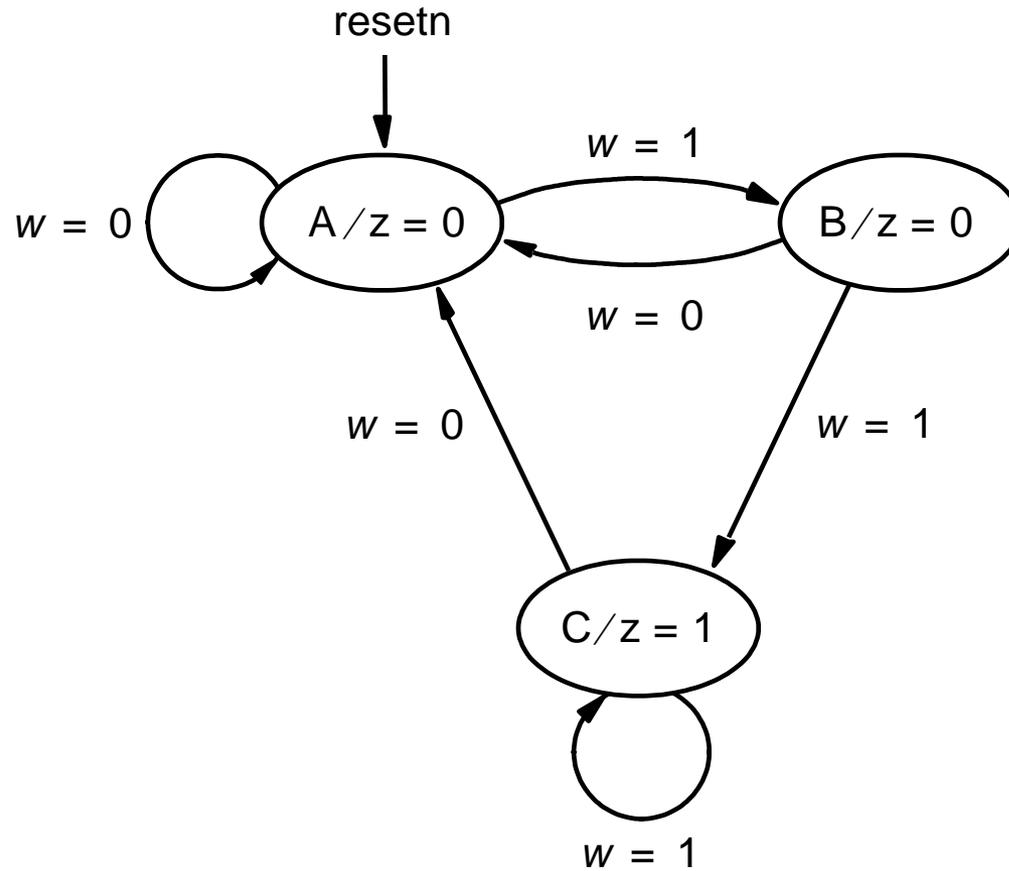
S0: No
elements
of the
sequence
observed

S1: “1”
observed

Moore & Mealy FSMs – Example 1



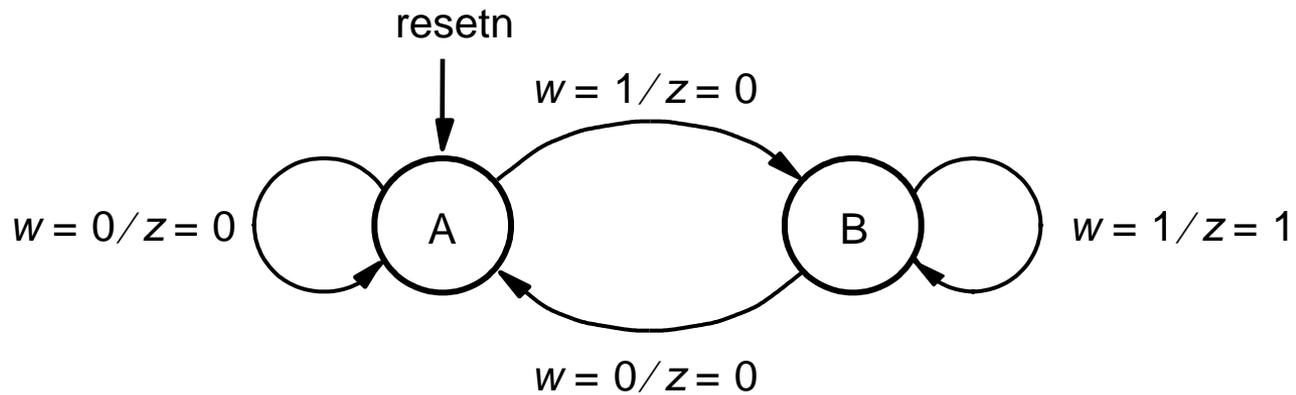
Moore FSM – Example 2: State diagram



Moore FSM – Example 2: State table

Present state	Next state		Output z
	$w = 0$	$w = 1$	
A	A	B	0
B	A	C	0
C	A	C	1

Mealy FSM – Example 3: State diagram



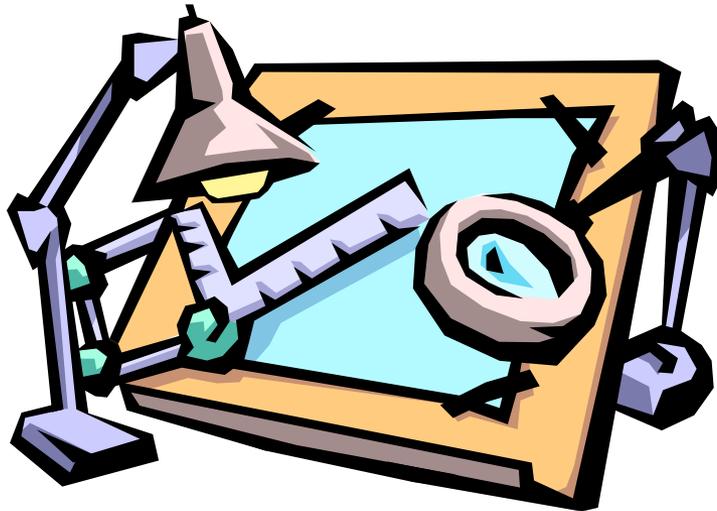
Mealy FSM – Example 3: State table

Present state	Next state		Output z	
	$w = 0$	$w = 1$	$w = 0$	$w = 1$
A	A	B	0	0
B	A	B	0	1

Sequential circuit design

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- Now let's reverse the process: In **sequential circuit design**, we turn some description into a working circuit.
 - We first make a state table or diagram to express the computation.
 - Then we can turn that table or diagram into a sequential circuit.



Sequence recognizers

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- A **sequence recognizer** is a special kind of sequential circuit that looks for a special bit pattern in some input.
- The recognizer circuit has only one input, X .
 - ▣ One bit of input is supplied on every clock cycle. For example, it would take 20 cycles to scan a 20-bit input.
 - ▣ This is an easy way to permit arbitrarily long input sequences.
- There is one output, Z , which is 1 when the desired pattern is found.
- Our example will detect the bit pattern “1001”:

Inputs: 1 1 1 0 0 1 1 0 1 0 0 1 0 0 1 1 0 ...

Outputs: 0 0 0 0 0 1 0 0 0 0 0 1 0 0 1 0 0 ...

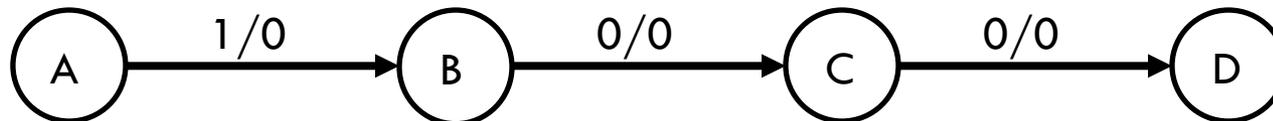
Here, one input and one output bit appear every clock cycle.

- This requires a sequential circuit because the circuit has to “remember” the inputs from previous clock cycles, in order to determine whether or not a match was found.

A basic state diagram

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- What state do we need for the sequence recognizer?
 - ▣ We have to “remember” inputs from previous clock cycles.
 - ▣ For example, if the previous three inputs were 100 and the current input is 1, then the output should be 1.
 - ▣ In general, we will have to remember occurrences of parts of the desired pattern—in this case, 1, 10, and 100.
- We'll start with a basic state diagram:



State	Meaning
A	None of the desired pattern (1001) has been input yet.
B	We've already seen the first bit (1) of the desired pattern.
C	We've already seen the first two bits (10) of the desired pattern.
D	We've already seen the first three bits (100) of the desired pattern.

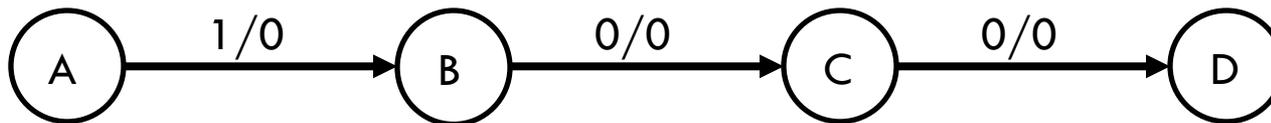
Step 1: Making a state table

- The first thing you have to figure out is precisely how the use of state will help you solve the given problem.
 - ▣ Make a state table based on the problem statement. The table should show the present states, inputs, next states and outputs.
 - ▣ Sometimes it is easier to first find a state diagram and then convert that to a table.
- This is usually the most difficult step. Once you have the state table, the rest of the design procedure is the same for all sequential circuits.
- Sequence recognizers are especially hard! They're the hardest example we'll see in this class, so if you understand this you're in good shape.

A basic state diagram

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- What state do we need for the sequence recognizer?
 - We have to “remember” inputs from previous clock cycles.
 - For example, if the previous three inputs were 100 and the current input is 1, then the output should be 1.
 - In general, we will have to remember occurrences of parts of the desired pattern—in this case, 1, 10, and 100.
- We’ll start with a basic state diagram:

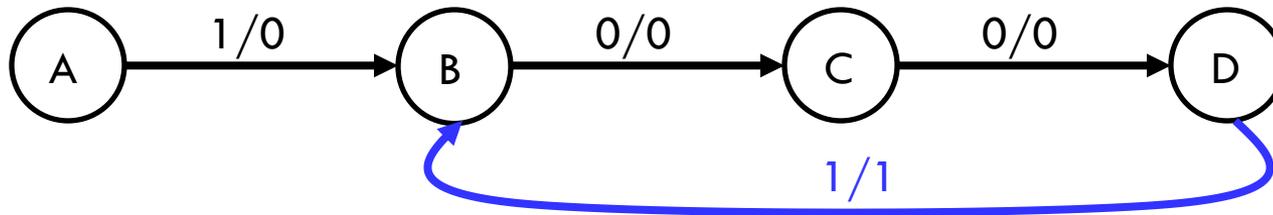


State	Meaning
A	None of the desired pattern (1001) has been input yet.
B	We've already seen the first bit (1) of the desired pattern.
C	We've already seen the first two bits (10) of the desired pattern.
D	We've already seen the first three bits (100) of the desired pattern.

Overlapping occurrences of the pattern

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- What happens if we're in state D (the last three inputs were 100), and the current input is 1?
 - The output should be a 1, because we've found the desired pattern.
 - But this last 1 could also be the start of another occurrence of the pattern! For example, 1001001 contains *two* occurrences of 1001.
 - To detect overlapping occurrences of the pattern, the next state should be B.

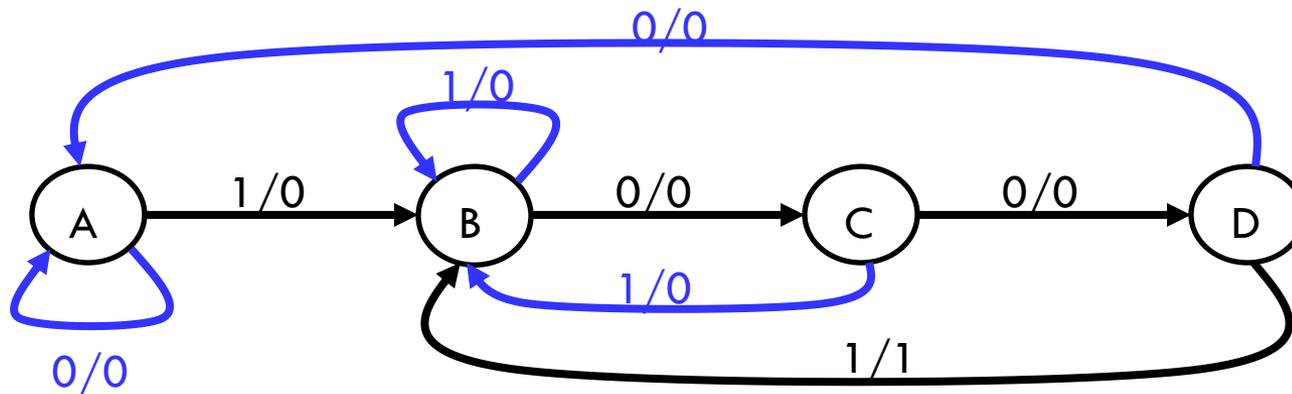


State	Meaning
A	None of the desired pattern (1001) has been input yet.
B	We've already seen the first bit (1) of the desired pattern.
C	We've already seen the first two bits (10) of the desired pattern.
D	We've already seen the first three bits (100) of the desired pattern.

Filling in the other arrows

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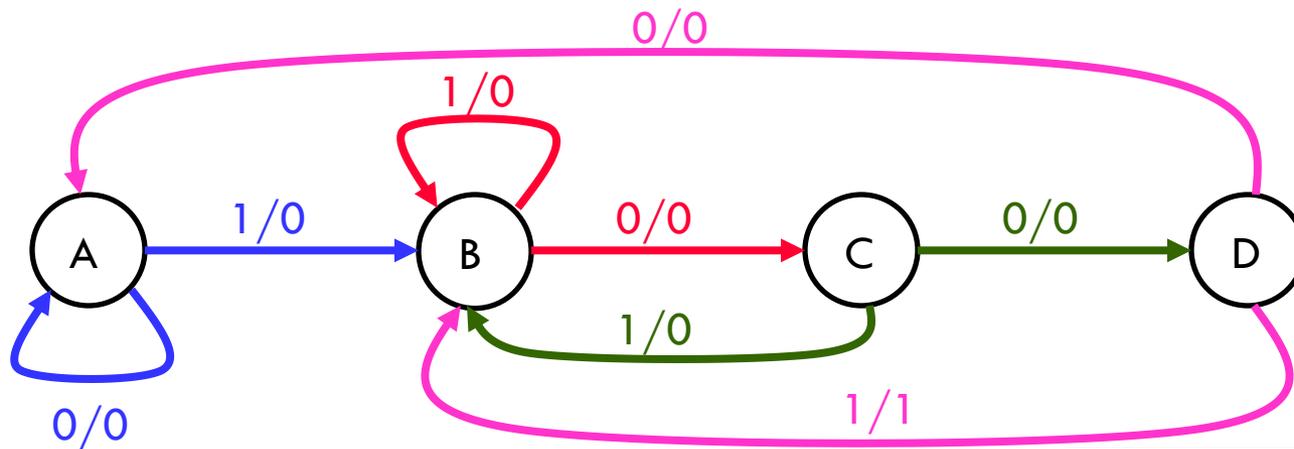
- Remember that we need *two* outgoing arrows for each node, to account for the possibilities of $X=0$ and $X=1$.
- The remaining arrows we need are shown in blue. They also allow for the correct detection of overlapping occurrences of 1001.



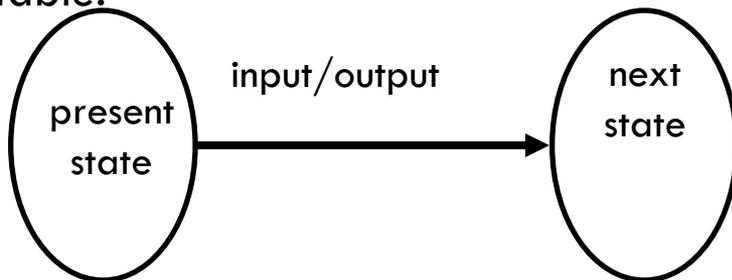
State	Meaning
A	None of the desired pattern (1001) has been input yet.
B	We've already seen the first bit (1) of the desired pattern.
C	We've already seen the first two bits (10) of the desired pattern.
D	We've already seen the first three bits (100) of the desired pattern.

Finally, making the state table

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Remember how the state diagram arrows correspond to rows of the state table:



Present State	Input	Next State	Output
A	0	A	0
A	1	B	0
B	0	C	0
B	1	B	0
C	0	D	0
C	1	B	0
D	0	A	0
D	1	B	1

Sequential circuit design procedure

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Step 1:

Make a state table based on the problem statement. The table should show the present states, inputs, next states and outputs. (It may be easier to find a state diagram first, and then convert that to a table.)

Step 2:

Assign binary codes to the states in the state table, if you haven't already. If you have n states, your binary codes will have at least $\lceil \log_2 n \rceil$ digits, and your circuit will have at least $\lceil \log_2 n \rceil$ flip-flops.

Step 3:

For each flip-flop and each row of your state table, find the flip-flop input values that are needed to generate the next state from the present state. You can use flip-flop excitation tables here.

Step 4:

Find simplified equations for the flip-flop inputs and the outputs.

Step 5:

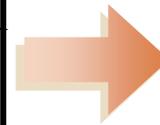
Build the circuit!

Step 2: Assigning binary codes to states

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- We have four states ABCD, so we need at least two flip-flops Q_1Q_0 .
- The easiest thing to do is represent state A with $Q_1Q_0 = 00$, B with 01, C with 10, and D with 11.
- The state assignment can have a big impact on circuit complexity, but we won't worry about that too much in this class.

Present State	Input	Next State	Output
A	0	A	0
A	1	B	0
B	0	C	0
B	1	B	0
C	0	D	0
C	1	B	0
D	0	A	0
D	1	B	1



Present State		Input X	Next State		Output Z
Q_1	Q_0		Q_1	Q_0	
0	0	0	0	0	0
0	0	1	0	1	0
0	1	0	1	0	0
0	1	1	0	1	0
1	0	0	1	1	0
1	0	1	0	1	0
1	1	0	0	0	0
1	1	1	0	1	1

Step 3: Finding flip-flop input values

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- Next we have to figure out how to actually make the flip-flops change from their present state into the desired next state.
- This depends on what kind of flip-flops you use!
- We'll use two JKs. For each flip-flop Q_i , look at its present and next states, and determine what the inputs J_i and K_i should be in order to make that state change.

Present State		Input X	Next State		Flip flop inputs				Output
Q_1	Q_0		Q_1	Q_0	J_1	K_1	J_0	K_0	Z
0	0	0	0	0					0
0	0	1	0	1					0
0	1	0	1	0					0
0	1	1	0	1					0
1	0	0	1	1					0
1	0	1	0	1					0
1	1	0	0	0					0
1	1	1	0	1					1

Finding JK flip-flop input values

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- For JK flip-flops, this is a little tricky. Recall the characteristic table:

J	K	Q(t+1)	Operation
0	0	Q(t)	No change
0	1	0	Reset
1	0	1	Set
1	1	Q'(t)	Complement

- If the present state of a JK flip-flop is 0 and we want the next state to be 1, then we have two choices for the JK inputs:
 - We can use JK=10, to explicitly set the flip-flop's next state to 1.
 - We can also use JK=11, to complement the current state 0.
- So to change from 0 to 1, we must set J=1, but K could be *either* 0 or 1.
- Similarly, the other possible state transitions can all be done in two different ways as well.

JK excitation table

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- An **excitation table** shows what flip-flop inputs are required in order to make a desired state change.

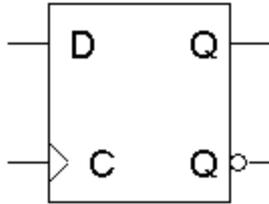
Q(t)	Q(t+1)	J	K	Operation
0	0	0	x	No change/reset
0	1	1	x	Set/complement
1	0	x	1	Reset/complement
1	1	x	0	No change/set

- This is the same information that's given in the characteristic table, but presented "backwards."

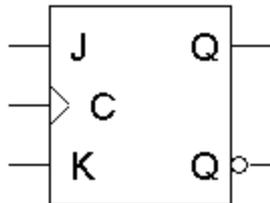
J	K	Q(t+1)	Operation
0	0	Q(t)	No change
0	1	0	Reset
1	0	1	Set
1	1	Q'(t)	Complement

Excitation tables for all flip-flops

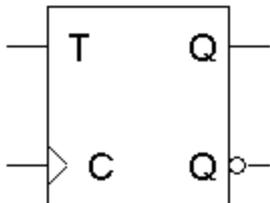
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Q(t)	Q(t+1)	D	Operation
0	0	0	Reset
0	1	1	Set
1	0	0	Reset
1	1	1	Set



Q(t)	Q(t+1)	J	K	Operation
0	0	0	x	No change/reset
0	1	1	x	Set/complement
1	0	x	1	Reset/complement
1	1	x	0	No change/set



Q(t)	Q(t+1)	T	Operation
0	0	0	No change
0	1	1	Complement
1	0	1	Complement
1	1	0	No change

Back to the example

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- We can now use the JK excitation table on the right to find the correct values for each flip-flop's inputs, based on its present and next states.

Q(t)	Q(t+1)	J	K
0	0	0	x
0	1	1	x
1	0	x	1
1	1	x	0

Present State		Input X	Next State		Flip flop inputs				Output Z
Q ₁	Q ₀		Q ₁	Q ₀	J ₁	K ₁	J ₀	K ₀	
0	0	0	0	0	0	x	0	x	0
0	0	1	0	1	0	x	1	x	0
0	1	0	1	0	1	x	x	1	0
0	1	1	0	1	0	x	x	0	0
1	0	0	1	1	x	0	1	x	0
1	0	1	0	1	x	1	1	x	0
1	1	0	0	0	x	1	x	1	0
1	1	1	0	1	x	1	x	0	1

Step 4: Find equations for the FF inputs and output

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- Now you can make K-maps and find equations for each of the four flip-flop inputs, as well as for the output Z.
- These equations are in terms of the present state and the inputs.
- The advantage of using JK flip-flops is that there are many don't care conditions, which can result in simpler MSP equations.

Present State		Input X	Next State		Flip flop inputs				Output Z
Q ₁	Q ₀		Q ₁	Q ₀	J ₁	K ₁	J ₀	K ₀	
0	0	0	0	0	0	x	0	x	0
0	0	1	0	1	0	x	1	x	0
0	1	0	1	0	1	x	x	1	0
0	1	1	0	1	0	x	x	0	0
1	0	0	1	1	x	0	1	x	0
1	0	1	0	1	x	1	1	x	0
1	1	0	0	0	x	1	x	1	0
1	1	1	0	1	x	1	x	0	1

$$J_1 = X' Q_0$$

$$K_1 = X + Q_0$$

$$J_0 = X + Q_1$$

$$K_0 = X'$$

$$Z = Q_1 Q_0 X$$

Step 5: Build the circuit

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- Lastly, we use these simplified equations to build the completed circuit.

$$J_1 = X' Q_0$$
$$K_1 = X + Q_0$$

$$J_0 = X + Q_1$$
$$K_0 = X'$$

$$Z = Q_1 Q_0 X$$

